

TABLE OF CONTENTS

PREFACE	4
PRINTING/REVISION HISTORY	4
1. EXPERIMENTAL MODAL ANALYSIS	1
1.1 Introduction	1
1.2 Experimental Modal Analysis Overview	2
1.3 Degrees of Freedom	5
1.4 Basic Assumptions	9
1.5 References	11
2. MODAL ANALYSIS THEORY	1
2.1 Introduction	1
2.2 Transform Relationships	1
2.2.1 Transform Properties	2
2.3 Single Degree of Freedom Systems	3
2.3.1 Time Domain: Impulse Response Function	6
2.3.2 Frequency Domain: Frequency Response Function	8
2.3.3 Laplace Domain: Transfer Function	12
2.4 Multiple Degree of Freedom Systems	19
2.5 Damping Mechanisms	25
2.6 References	26
3. HISTORY OF EXPERIMENTAL MODAL ANALYSIS	1
3.1 Introduction	1
3.2 Data Acquisition Classification	2
3.2.1 Sinusoidal Input-Output Method	4
3.2.1.1 Forced Normal Mode Excitation Method	4
3.2.1.2 Forced Response Decomposition Method	6
3.2.2 Frequency Response Function Method	8
3.2.2.1 Theory	9
3.2.3 Damped Complex Exponential Method	11
3.2.3.1 Ibrahim Time Domain (ITD) Approach	12
3.2.3.2 Poly-Reference Time Domain (PTD) Approach	13
3.2.3.3 Eigensystem Realization Algorithm Approach	14
3.2.4 Mathematical Input-Output Model Method	16
3.2.4.1 Autoregressive Moving Average Approach	16
3.2.4.2 Reduced Structural Matrix Approach	18
3.3 References	20
4. MODAL DATA ACQUISITION	1
4.1 Introduction	1
4.2 Errors	3
4.3 Analog to Digital Conversion	

	4
4.3.1	Sampling	5
4.3.2	Quantization	9
4.3.3	ADC Implementation Issues	14
4.3.4	ADC Errors	17
	4.3.4.1 Aliasing	17
	4.3.4.2 Other Types of ADC Error	19
4.4	Discrete Fourier Transform	20
	4.4.1 DFT/FFT Errors	24
	4.4.1.1 Leakage Error	24
4.5	Increased Frequency Resolution	30
4.6	Weighting Functions	35
4.7	Averaging	39
	4.7.1 General Averaging Methods	40
	4.7.1.1 Linear Averaging	40
	4.7.1.2 Magnitude Averaging	41
	4.7.1.3 Root-Mean-Square (RMS) Averaging	42
	4.7.1.4 Exponential Averaging	43
	4.7.1.5 Stable Averaging	44
	4.7.1.6 Peak Hold	44
	4.7.2 Estimation of Frequency Response Functions	44
	4.7.2.1 Asynchronous Signal Averaging	46
	4.7.2.2 Synchronous Signal Averaging	46
	4.7.2.3 Cyclic Signal Averaging	47
	4.7.2.3.1 Theory of Cyclic Averaging	49
	4.7.2.3.2 Practical Example	58
	4.7.3 Special Types of Signal Averaging	65
	4.7.3.1 Overlapping Time Records	65
4.8	Transducer Considerations	70
4.9	References	75
5.	FREQUENCY RESPONSE FUNCTION MEASUREMENTS	1
5.1	Introduction	1
5.2	Frequency Response Function Estimation	3
	5.2.1 Noise/Error Minimization	5
	5.2.2 Single Input FRF Estimation	8
	5.2.3 Multiple Input FRF Estimation	16
	Example: H_1 Technique: Two Inputs/One Output Case	25
	5.2.3.1 Multiple Input Force Analysis/Evaluation	29
5.3	Excitation	35
	5.3.1 Excitation Assumptions	38
	5.3.2 Terminology and Nomenclature	42
	5.3.3 Classification of Excitation	45
	5.3.4 Random Excitation Methods	47
	Hybrid Random Excitation Methods	

	5.3.5	Deterministic Excitation Methods	55
	5.3.6	Excitation Example - H-Frame	60
	5.3.7	Impact Excitation	70
5.4		Structural Testing Conditions	74
5.5		Practical Measurement Considerations	76
5.6		References	77
6.		MODAL PARAMETER ESTIMATION	1
6.1		Introduction	1
6.2		Definition: Modal Parameters	2
6.3		Modal Identification Concepts	3
	6.3.1	Concept: Data Domain	7
	6.3.2	Concept: Model Order Relationships	8
	6.3.3	Concept: Fundamental Measurement Models	10
	6.3.4	Concept: Characteristic Space	11
	6.3.5	Concept: Fundamental Modal Identification Models	18
	6.3.6	Concept: Two Stage Linear Solution Procedure	24
	6.3.7	Concept: Data Sieving/Filtering	29
	6.3.8	Concept: Equation Condensation	29
	6.3.9	Concept: Coefficient Condensation	31
	6.3.10	Concept: Model Order Determination	34
		6.3.10.1 Error Chart	36
		6.3.10.2 Stability Diagram	37
		6.3.10.3 Mode Indication Functions	39
		6.3.10.3.1 Multivariate Mode Indication Function (MvMIF)	39
		6.3.10.3.2 Complex Mode Indication Function (CMIF)	40
		6.3.10.4 Rank Estimation	44
	6.3.11	Concept: Residuals	45
6.4		SDOF Approximate Algorithms	48
	6.4.1	Operating Vector Estimation	49
	6.4.2	Complex Plot (Circle Fit)	53
	6.4.3	Two Point Finite Difference Formulation	57
	6.4.4	Least Squares (Local) SDOF Method	60
	6.4.5	Least Squares (Global) SDOF Method	62
6.5		Modal Identification Algorithms	63
	6.5.1	High Order Time Domain Algorithms	63
		6.5.1.1 Complex Exponential Algorithm: Example	65
		6.5.1.1.1 SDOF Numerical Example	67
	6.5.2	First Order Time Domain Algorithms	72
	6.5.3	Second Order Time Domain Algorithms	73
	6.5.4	High Order Frequency Domain Algorithms	74
		6.5.4.1 Rational Fraction Polynomial: Example	75
		6.5.4.1.1 SDOF Numerical Example	78
		6.5.4.2 Orthogonal Polynomial Concepts	81
		Chebyshev Orthogonal Polynomials	

	Legendre Orthogonal Polynomials	84
6.5.5	First Order Frequency Domain Algorithms	87
6.5.6	Second Order Frequency Domain Algorithms	88
6.6	Residue Estimation	90
6.6.1	Time Domain Estimation (Single Reference)	90
6.6.2	Time Domain Estimation (Multiple References)	91
6.6.3	Frequency Domain Estimation (Single Reference)	92
6.6.4	Frequency Domain Estimation (Single Reference With Residuals)	93
6.6.5	Frequency Domain Estimation (Multiple References)	94
6.7	Summary - Future Trends	95
6.8	References	95
7.	MODAL DATA PRESENTATION/VALIDATION	1
7.1	Measurement Synthesis	1
7.2	Visual Verification	4
7.3	Finite Element Analysis	6
7.4	Modal Vector Orthogonality	6
7.5	Modal Vector Consistency	8
7.6	Modal Modification Prediction	14
7.7	Modal Complexity	14
7.8	Modal Phase Colinearity and Mean Phase Deviation	15
7.9	References	15
Appendix A:	Least Squares Method	1
A.1	Correlation Coefficient	6
A.2	Examples	7
A.2.1	Example 1	7
A.2.2	Example 2	9
A.3	References	11
Appendix B:	Singular Value Decomposition	1
B.1	References	4
Appendix C:	Bibliography	

..... 1
LIST OF FIGURES

Figure 1-1. Experimental Modal Analysis Example	4
Figure 1-2. Degrees of Freedom of a Rigid Body	6
Figure 2-1. Zoom Transform Process	3
Figure 2-2. Single Degree of Freedom System	3
Figure 2-3. Time Domain: Impulse Response Function	7
Figure 2-4. Frequency Response Function (Real/Imaginary Format)	10
Figure 2-5. Frequency Response Function (Magnitude/Phase Format)	11
Figure 2-6. Frequency Response Function (Log Magnitude/Phase Format)	11
Figure 2-7. Transfer Function (Real/Imaginary Format)	15
Figure 2-8. Transfer Function (Magnitude/Phase Format)	16
Figure 2-9. Transfer Function (Log Magnitude/Phase Format)	17
Figure 2-10. Transfer Function - LaPlace Plane Projection)	18
Figure 2-11. Multi-Degree of Freedom System)	19
Figure 4-1. Shannon Sampling Theorem	6
Figure 4-2. Basic Sampling Relationships	6
Figure 4-3. Rayleigh's Criterion	7
Figure 4-4. Quantization: 3 Bit Analog to Digital Converter	10
Figure 4-5. Quantization: ADC Input Optimization (Unwanted DC)	11
Figure 4-6. Quantization: ADC Input Optimization (Unwanted Harmonic)	11
Figure 4-7. 1.2 Hertz AC Coupling Characteristics (Magnitude and Phase)	12
Figure 4-8. Variable Sample Frequency ADC Design	14
Figure 4-9. Fixed Sample Frequency ADC Design	15
Figure 4-10. Delta-Sigma ADC Design	16
Figure 4-11. Aliasing Example	17
Figure 4-12. Aliasing Contribution (Shannon Sampling Theorem Limit)	18
Figure 4-13. Discrete Fourier Transform Concept	20
Figure 4-14. Time Domain Function: Theoretical Harmonic	26

Figure 4-15. Time Domain Function: Theoretical Window	26
Figure 4-16. Time Domain Function: Multiplication of Signals	26
Figure 4-17. Frequency Domain: Theoretical Harmonic	28
Figure 4-18. Frequency Domain: Theoretical Window	28
Figure 4-19. Frequency Domain: Convolved Signals	28
Figure 4-20. Frequency Domain: Periodic Signal	29
Figure 4-21. Frequency Domain: Nonperiodic Signal	29
Figure 4-22. Increased Frequency Resolution	31
Figure 4-23. Increased Frequency Resolution	33
Figure 4-24. Increased Frequency Resolution	33
Figure 4-25. Typical Weighting Function - Boxcar (P000) Window	35
Figure 4-26. Typical Weighting Functions - Hanning (P110) Window	37
Figure 4-27. Typical Weighting Functions - Flattop (P301) Window	37
Figure 4-28. Typical Weighting Function - Hanning (P110) Window	37
Figure 4-29. Typical Weighting Function - Flattop (P301) Window	38
Figure 4-30. Contiguous Time Records (Periodic Signal)	48
Figure 4-31. Averaged Time Records (Periodic Signal)	48
Figure 4-32. Contiguous Time Records (Non-Periodic Signal)	48
Figure 4-33. Averaged Time Records (Non-Periodic Signal)	48
Figure 4-34. Cyclic Averaging ($N_c = 4$) with Uniform Window	52
Figure 4-35. Cyclic Averaging ($N_c = 4$) with Hann Window	52
Figure 4-36. Uniform Window Characteristics	53
Figure 4-37. Cyclic Averaging ($N_c = 2$) with Uniform Window	53
Figure 4-38. Cyclic Averaging ($N_c = 4$) with Uniform Window	54
Figure 4-39. Hann Window Characteristics	54
Figure 4-40. Cyclic Averaging ($N_c = 2$) with Hann Window	55
Figure 4-41. Cyclic Averaging ($N_c = 4$) with Hann Window	55
Figure 4-42. Contiguous Time Records	56
Figure 4-43. Averaged Time Records	57
Figure 4-44. Contiguous Time Records with Hann Window	57
Figure 4-45. Averaged Time Records with Hann Window	58

Figure 4-46. Case I: Asynchronous Averaging	60
Figure 4-47. Case II: Asynchronous Averaging With Hann Window	61
Figure 4-48. Case III: Cyclic Averaging	62
Figure 4-49. Case IV: Cyclic Averaging With Hann Window	63
Figure 4-50. Overlap Processing: Zero Overlap	65
Figure 4-51. Overlap Processing: Fifty Percent Overlap	66
Figure 4-52. Random Decrement Averaging	68
Figure 4-53. Calibration Methods	73
Figure 4-54. FRF Magnitude: Calibration Errors	74
Figure 4-55. FRF Magnitude: Calibration Errors Corrected	74
Figure 5-1. Two Input, Two Output FRF Concept	5
Figure 5-2. Least Squares Concept	6
Figure 5-3. System Model: Single Input	8
Figure 5-4. FRF and Corresponding Ordinary Coherence Function	13
Figure 5-5. Ordinary Coherence Relationship - Averaging	15
Figure 5-6. System Model: Multiple Inputs	19
Figure 5-7. Two Input, One Output Model	25
Figure 5-8. AutoPower Spectrum of Input Forces	32
Figure 5-9. Principal (Virtual) Force Spectrum	33
Figure 5-10. Typical Test Configuration: Shaker	35
Figure 5-11. Typical Test Configuration: Impact Hammer	36
Figure 5-12. Input Spectrum Example	40
Figure 5-13. Total Contiguous Time Per power Spectral Average (Ensemble)	44
Figure 5-14. Signal Energy Content - Pure Random	49
Figure 5-15. Signal Energy Content - Pseudo Random	49
Figure 5-16. Signal Energy Content - Periodic Random	50
Figure 5-17. Signal Energy Content - Burst Random	51
Figure 5-18. Burst Random - Signal to Shaker	52
Figure 5-19. Burst Random - Signal from Load Cell (Voltage Feedback)	52
Figure 5-20. Burst Random - Signal from Accelerometer	53
Figure 5-21. Signal Energy Content - Burst Pseudo Random	55

Figure 5-22. Signal Energy Content - Burst Periodic Random	55
Figure 5-23. Typical Chirp Signal - Time Domain	56
Figure 5-24. Typical Chirp Signal - Frequency Domain	57
Figure 5-25. Case 1: Random Excitation with Hann Window	62
Figure 5-26. Case 2: Random Excitation with Hann Window and Cyclic Averaging	63
Figure 5-27. Case 3: Burst Random Excitation with Cyclic Averaging	63
Figure 5-28. Case 4: Pseudo Random Excitation	64
Figure 5-29. Case 5: Periodic Random Excitation	64
Figure 5-30. Case 6: Pseudo Random Excitation	65
Figure 5-31. Case 7: Periodic Random Excitation	65
Figure 5-32. Case 8: Burst Pseudo Random Excitation with Cyclic Averaging	66
Figure 5-33. Case 9: Burst Periodic Random Excitation with Cyclic Averaging	66
Figure 5-34. Case 10: Burst Random Excitation with Cyclic Averaging	67
Figure 5-35. Case 11: Random Excitation with Hann Window	67
Figure 5-36. Case 12: Random Excitation with Hann Window and Cyclic Averaging	68
Figure 5-37. Case 13: Pseudo Random Excitation with Cyclic Averaging	68
Figure 5-38. Case 14: Periodic Random Excitation with Cyclic Averaging	69
Figure 5-39. Typical Force Windows	71
Figure 5-40. Typical Response Windows	73
Figure 6-1. MDOF - SDOF Superposition (Positive Frequency Poles)	3
Figure 6-2. MDOF - SDOF Superposition (Positive Frequency Poles)	4
Figure 6-3. MDOF - SDOF Superposition (Positive - Negative Frequency Poles)	5
Figure 6-4. Conceptualization of Modal Characteristic Space	11
Figure 6-5. Characteristic Space: Column of Measurements	14
Figure 6-6. Characteristic Space: Columns of Measurements	14
Figure 6-7. Characteristic Space: Row of Measurements	15
Figure 6-8. Characteristic Space: Rows of Measurements	16
Figure 6-9. Characteristic Space: Temporal Measurements	16
Figure 6-10. Characteristic Space: Temporal Measurements	17
Figure 6-11. Underdetermined Set of Linear Equations	26
Figure 6-12. Underdetermined Set of Linear Equations	26

Figure 6-13. Determined Set of Linear Equations	27
Figure 6-14. Overdetermined Set of Linear Equations	27
Figure 6-15. Model Order Determination: Error Chart	36
Figure 6-16. Model Order Determination: Stability Diagram	38
Figure 6-17. Multivariate Mode Indication Function	40
Figure 6-18. Complex Mode Indication Function	43
Figure 6-19. Model Order Determination: Rank Estimation	44
Figure 6-20. Residual Effects From Adjacent Poles	45
Figure 6-21. Modal Vectors from the Imaginary Part of the FRF	48
Figure 6-22. Single Degree of Freedom Method - Magnitude/Phase	51
Figure 6-23. Single Degree of Freedom Method - Log Magnitude/Phase	51
Figure 6-24. Single Degree of Freedom Method - Real/Imaginary	52
Figure 6-25. Single Degree of Freedom Method - Real versus Imaginary	55
Figure 6-26. Typical Impulse Response Function	65
Figure 6-27. Case I: Impulse Response Function	69
Figure 6-28. Case II: Impulse Response Function	70
Figure 6-29. Case III: Impulse Response Function	71
Figure 6-30. Frequency Response Function, SDOF Example	79
Figure 6-31. Power Polynomials	82
Figure 6-32. Power Polynomials (Normalized Frequency)	83
Figure 6-33. Chebyshev Orthogonal Polynomials	84
Figure 6-34. Legendre Orthogonal Polynomials	87
Figure 7-1. Typical FRF Synthesis	2
Figure 7-2. Normalized Error - FRF Synthesis	3
Figure 7-3. Visual Verification of Modal Vectors	5
Figure A-1. Straight Lines Fitting the Data	1
Figure A-2. Errors in Least Squares Estimation	3
Figure A-3. Variations in Data	6
Figure A-4. Least Squares Fit of Data	8

LIST OF TABLES

Table 2-1. Modal Scaling Units	25
Table 4-2. Digitization Equations ($F_{\max} = F_{Nyq}$)	8
Table 4-3. Comparison of Averaging Methods	43
Table 4-4. Transducer Mounting Methods	71
Table 5-5. Frequency Response Function Formulations	4
Table 5-6. Summary of Frequency Response Function Estimation Models	7
Table 5-7. Excitation Characteristics	54
Table 5-8. Summary of Excitation Signals	59
Table 5-9. Test Cases - Excitation/Averaging/DSP Parameters	60
Table 6-10. Summary of Modal Parameter Estimation Algorithms	22
Table 6-11. Summary of Modal Parameter Estimation Acronyms	22
Table A-12. x and y Values for Least Squares Fit	7